

1 A. TITLE OF THE INVENTION

2 Apparatus and Method for Holding an Object

3 B. CROSS-REFERENCE TO RELATED APPLICATIONS

4 Not Applicable

5 C. STATEMENT REGARDING FEDERALLY SPONSORED RESEARCH/DEVELOPMENT

6 The present invention does not involve any form of federally sponsored research or
7 development.

8 D. BACKGROUND OF THE INVENTION

9 Devices and methods for holding objects, particularly by a clip, are known. Clips come in a
10 variety of designs depending on the type and thickness of the object or objects being held. Many
11 clips are designed for use with papers. Other clips have been designed to hold x-rays, fabric, cloth,
12 pictures, posters, decorations, and so forth. Complex clips designs have special surfaces to distribute
13 the grasping forces and protect the held object from damage. In general, clips are formed by two
14 elastic members that contact or are proximately close to each other. The members are often co-
15 planar, or approximately parallel to each other. Clips are formed from multiple components or from
16 a complex arrangement of a single component. For example, metals clips can be formed by
17 assembling two metal pieces or by bending a metal wire to form adjacent members. Plastic clips can
18 be formed by the co-extrusion of a soft and hard synthetic resin or by special molding that creates
19 internal stress to bias members towards each other.

20 The clip business is competitive, and clips designs that minimize raw materials and
21 manufacturing complexity are desirable. A single piece clip can be inexpensively manufactured by
22 injection molding of a thermoplastic provided the elastic members are formed to produce a desirable
23 holding tension without being in contact with each other.

24 Accordingly, there is a need for an apparatus for and method of holding an object, which
25 apparatus includes a base having an opening and a top member having a grasping end that extends

DECLARATION

As the below named inventor, I hereby declare that my respective residence, mailing address, and citizenship is as stated below.

I believe I am the sole, original and first inventor of the subject matter that is claimed and for which a patent is sought on the invention entitled:

APPARATUS AND METHOD FOR HOLDING AN OBJECT

The specification for the above named device is attached hereto.

I hereby state that I have reviewed and understand the contents of the above identified specification, including the claims. I acknowledge the duty to disclose information which is material to the patentability as defined in Title 37 of the Code of Federal Regulations section 1.56.

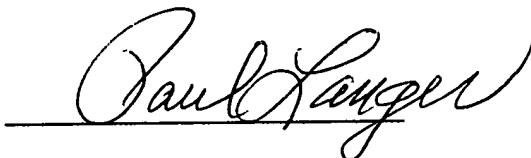
I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under 18 U.S.C. 1001 and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Name: Paul Langer

Residence: 429 Torrey Pines Way
Vernon Hills, Illinois 60061

Citizenship: United States citizen

Signature:

A handwritten signature in black ink, appearing to read "Paul Langer", is written over a horizontal line. The signature is fluid and cursive, with a large, stylized "P" at the beginning.

POWER OF ATTORNEY

I hereby appoint Timothy J. Fullin J.D., LL.M., registration number 50685, as my attorney to prosecute the patent application attached hereto, for the device entitled:

APPARATUS AND METHOD FOR HOLDING AN OBJECT

I further authorize Timothy J. Fullin J.D., LL.M., registration number 50685, to transact all business in the United States Patent and Trademark Office connected therewith.

Please address all related correspondence to this address:

Timothy J. Fullin J.D., LL.M.

Fullin Legal Services LLC

711 North Milwaukee Avenue

Libertyville, Illinois 60048

Telephone: (847) 573-9880

Fax: (847) 573-9882

I am the applicant/inventor of the above identified application/invention.

Signature: Paul Langer

Printed Name: Paul Langer

Date: 1/14/04

26 through the opening, and which method holds an object by grasping it between the grasping end of
27 the top member and a base grasping end having the opening.

28 **E. BRIEF SUMMARY OF THE INVENTION**

29 An apparatus and a method for grasping and holding an object are provided. The apparatus
30 includes a base having an opening, a bendable fulcrum, and a top member having a grasping end that
31 extends through the opening. The steps of the method include squeezing a handle end of the
32 apparatus to separate grasping end members, inserting an object between the grasping end members,
33 and releasing the handle end to allow tension in the apparatus to grab the object with the grasping
34 end members.

35 **F. BRIEF DESCRIPTION OF THE DRAWINGS**

36 FIG. 1A illustrates a top view of an apparatus having a base with an opening and a top
37 member that extends into and through the opening.

38 FIG. 1B illustrates a bottom view of an apparatus having a base with an opening and a top
39 member that extends into and through the opening.

40 FIG. 2 illustrates an embodiment of an apparatus that has a gripping member that extends
41 below the plane of a base bottom.

42 FIG. 3 is a flowchart illustrating a method for use in holding an object with a clip.

43 **G. DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT**

44 The present invention includes an apparatus and method for holding an object, such as a clip.
45 Clips are made of materials that have tensile strength such as metal or plastic, and typically include
46 two members that are elastically connected. The two members are separated such that an inherent
47 elasticity creates a tension for holding objects in place between the two members. The grasping
48 members include a base having an opening and a top member that extends into the opening. A
49 bendable fulcrum elastically connects the two members. Squeezing a handle end of the clip

50 separates the grasping ends of the two members, and a tension from the inherent elasticity in the
51 bendable fulcrum can hold an object when the handle end of the clip is released.

52 A clip that comprises a base 101 that includes a grasping end 103, and a handle end 105 is
53 shown in FIG. 1A. The base 101 has an opening 107 in the grasping end 103. As shown in FIG.
54 1A, the base 101 is planar and consists of four side members that form a rectangular base 101 and a
55 rectangular opening 107. In the embodiment, a second rectangular opening 109 is also formed in the
56 handle end 105 of the base. Alternatively, the base and openings can be other geometric shapes such
57 as circles, triangles, ellipses, non-regular shapes, and so forth. In addition, the base can be formed
58 with a single opening 107 such that the handle end 105 is solid and without an opening.

59 A top member 113 is elastically connected the base 101 by a bendable fulcrum 111. A
60 grasping end 115 of the top member extends into the opening 107 and can extend to or below a plane
61 formed by the bottom of the base 101.

62 As shown in FIG. 2B, a gripping member 119 for holding the object can be formed at a tip of
63 the grasping end 115. Supports 121 and 123 can be attached between the base 105 and the bendable
64 fulcrum 111. The supports stiffen the attachment of the fulcrum to the base and limit the bending of
65 the fulcrum to a portion near the attachment to the top member 113. The fulcrum 111 can have a
66 fillet where the fulcrum is attached to the top member 113 for added strength.

67 The holding of an object by the apparatus is initiated by squeezing the handle end of the clip.
68 The handle end of the clip includes the top member handle end 117 that is squeezed towards the base
69 handle end 105. The top member 113 rotates on the bendable fulcrum 111 which causes the top
70 member grasping end 115 to separate from the base grasping end 103. As the grasping ends
71 separate, tension results from the inherent elasticity in the bendable fulcrum 111, the base 101, and
72 the top member 113. An object is inserted between the separated grasping ends, 103 and 115, and
73 the handle ends, 105 and 117, are released. The object is grasped by the grasping ends, 103 and 115,
74 and held by tension from the inherent elasticity that remains from the clip in a partially bent position.

75 An embodiment shown in FIG. 2 depicts a side view of a single piece clip. A base 201 has a
76 grasping end with a single opening (not shown) and a solid handle end 205 without an opening.
77 Alternatively, the handle end 205 can be designed to facilitate surface mounting the clip by the
78 incorporation of a hole for a nail or screw, an adhesive backing, and so forth. The top member 213 is
79 supported on a bendable fulcrum 225. The bendable fulcrum 225 has pyramidal shape that is wider
80 at a fulcrum bottom 227. The pyramidal shape stiffens and strengthens supports for the bendable
81 fulcrum. The width of the pyramidal shape may extend across the width of the top member 213, and
82 the height of the pyramidal shape may be increased or decreased to accommodate the holding of
83 different size objects.

84 The grasping end 215 of the top member 213 extends below a plane formed by the bottom of
85 the base 201. A gripping tip 219 that is formed to grab the object is attached to the top member
86 grasping end 215. The gripping tip 219 can incorporate grooves or other formations and structures
87 to facilitate the holding of the object by the clip.

88 A flowchart that illustrates a method for use with holding an object with a clip is shown in
89 FIG. 3. At step 301, the handle ends of the base and top member, 105 and 117, are squeezed
90 towards each other. The squeezing causes the top member 113 to rotate around the bendable
91 fulcrum 111 such that the grasping ends of the base and the top member, 103 and 115, move away
92 from respective starting positions and become separated. At step 303, an object is placed in between
93 the separated grasping ends, 103 and 115. Transversing the base opening 107 by the object is a
94 desirable position for the object. Alternatively, the object need not transverse the opening 107;
95 however, there may be some loss in holding effectiveness.

96 At step 305, the handle ends of the base and top member, 105 and 117, are released. The
97 inherent elasticity of the bendable fulcrum 111, the base 101, and the top member 113 causes the
98 grasping ends, 103 and 115, to move towards respective starting positions. As the grasping ends,
99 103 and 115, move, the object is contacted, grasped, and held by the grasping ends.

100 An advantage of the present invention is the formation of a single-piece clip that can be
101 manufactured by injection molding of a single thermoplastic. A single-piece clip is less complicated
102 to manufacture than clips that require assembly of two or more clip components. A clip made of one
103 material eliminates complex molding of multiple materials and the need for additional raw material
104 inventory. The clip is formed from non-contacting and non-coplanar members and can be easily
105 manufacture by injection molding, and there is no need to form the clip with inherent tension. The
106 clip design is also amiable to modification to facilitate the holding of different types or number of
107 objects. For example, the height of the bendable fulcrum may be adjusted to accommodate different
108 size objects. Finally, the design uses inexpensive plastics as compared to metal.

109 The present invention can be embodied in other specific forms without departing from its
110 spirit or essential characteristics. The described embodiments are to be considered in all respects
111 only as illustrative and not restrictive. All changes that come within the meaning and range of
112 equivalency of the claims are to be embraced within their scope.